Loosely Coupled Communication in Actor Systems

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### Motivation

- Internet of Things (IoT)
  - Vulnerable
  - Low-powered & lossy connections
- Internet-wide systems
  - Software should scale on demand
  - No downtime due to failure of subsystems
  - Dynamic, world-wide deployment
    - Unknown when the code is written

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2 libcppa

**3** Loosely Coupled Communication

- 4 Use Cases
- 5 Challenges
- 6 Conferences & Key Players



Actors are concurrent entities, that ...

- Communicate via message passing
- Do not share state
- Can create ("spawn") new actors
- Can monitor other actors

## Benefits



- High-level, explicit communication: no locks, no implicit sharing
- Applies to both concurrency and distribution
  - Divide workload by spawning actors
  - Interact via network-transparent messaging
  - Run transparently on heterogenous hardware
- Failure semantics
  - Links / Monitors
  - Hierarchical error management
  - Re-deployment at runtime



## Implementations



### Erlang

- Designed by Joe Armstrong at Ericsson in 1986
- De-facto implementation of the actor model
- Wide-spread use
- Inspired other implementations
- Akka
  - Library for Scala based on the actor model
  - Initiated by Jonas Bonér in 2009
  - Developed by Typesafe Inc.
  - Included in the standard library

#### libcppa





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### Features

- Developed by iNET working group at the HAW
- libcppa is an actor system based on C++11
- Efficient program execution
  - Low memory footprint
  - Fast, lock-free mailbox implementation
- Targets both low-end and high-performance computing
  - Embedded HW, e.g., running RIOT (http://www.riot-os.org)
  - Large multi-core systems
- Uses internal DSL for pattern matching of messages
- Transparent integration of OpenCL-based actors



### Example



```
void math server() {
  become (
    on(atom("plus"), arg match) >> [](int a, int b) {
      return make cow tuple(atom("result"), a + b);
  );
void math client(actor ptr ms) {
  sync send(ms, atom("plus"), 40, 2).then(
    on(atom("result"), arg match) >> [=](int result){
      cout << "40 + 2 = " << result << endl;
  );
int main()
          {
  spawn(math client, spawn(math server));
  // ...
```

# Linking Actors



```
void bob fun(); // will fail
void alice fun() {
  auto bob = spawn<linked>(bob fun);
  send(bob, "hello bob");
  become ( /* will bob ever call back? */ );
}
void carl() {
  self->trap exit(true);
  auto alice = spawn<linked>(alice fun);
  become (
    on(atom("EXIT"), arg match) >> [](uint32 t r) {
      if (r != exit reason::normal)
        cout << "something went wrong..." << endl;</pre>
 );
```





#### 2 libcppa

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## Characteristics



- No global state
- Orchestration of independent systems
- Highly scalable
  - Performance depends on cores / nodes
  - Dynamic acquisition of resources based on demand
- Facade-like interfaces
  - Unknown implementation
  - Based on message content
- Suitable for long-distance traffic
  - Unreliable connections
  - Changing topology
  - Tolerant to interference
  - Asynchronous





2 libcppa

3 Loosely Coupled Communication



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## Safest





- Cooperation between:
  - France & Germany
  - Daviko, Forschungsforum Öffentliche Sicherheit, Fraunhofer FOKUS, FU Berlin, HAW Hamburg, INRIA, SAGEM
- Deployed at the airport Berlin Brandenburg

## Safest



- Area surveillance system
- Resilient against malfunctions of components
- Respect privacy of citizens
- Distributed collection of anonymized data
- Stepwise evaluation towards central event processing
- Alerts the operator and/or the general public
- Nodes run RIOT & libcppa
  - High-Level modeling & development in the actor model
  - Development & tests on desktop systems
  - Seamless deployment to nodes

# Publish/Subscribe



- Scalability
- Decoupled in space / time
- Easy way to deploy redundancy
- Examples:
  - Multicast
  - Information Centric Networking
  - Key-value storage





2 libcppa

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### Challenges Security



- Verify identity of participants
- Ensure integrity of received messages
- Obtain robustness
- Find solutions for a decentralized system
- Changes have local impact

### Challenges Fault-tolerance



- Implement monitors/links for different scenarios
  - Multicast
  - Internet-wide systems
  - Low-powered & lossy connections
- Handle unreliable connections
- Deploy reliable services

### Challenges Communication



- Communicate with unknown systems
  - Rendezvous processes
- Minimize communication overhead
- Failures in pub/sub environments
- Error propagation in non-hierarchical actor systems





2 libcppa

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## Conferences



- C++Now
  - Focused on C++
  - May 2014 in Aspen, Colorado
- $\blacksquare Splash \rightarrow Agere!$ 
  - Special Interest Group of ACM focused on Programming Languages
  - Actors, Agents, and Decentralized Control
- ICDCS
  - International Conference on Distributed Computing Systems
  - June / July 2014 in Spain
- PODC
  - ACM Symposium on Principles of Distributed Computing
  - July 2014 in Paris
- USENIX OSDI
  - USENIX Symposium on Operating Systems Design and Implementation
  - October 2014 in Broomfield, Colorado

# Key Players



#### Carl Hewitt

- Initial paper on actors
- Worked on actor model in 1973
- Gul Agha
  - Doctoral student of Hewitt
  - University of Illinois
  - On the Steering committee of the Agere
- Joe Armstrong
  - Developed Erlang in 1986



- Martin Odersky
  - Professor at the École polytechnique fédérale de Lausanne (EPFL)
  - Developed Scala
- Philipp Haller
  - PhD in Computer Science from EPFL
  - Developed original actor implementation for Scala
- Jonas Bonér
  - Developed Akka
- Viktor Klang
  - Technical lead for the Akka project

Odersky, Bonér and Klang are part of Typesafe, a company focused on "Reactive Programming".



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### Control Thank you for your attention. Questions?

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